

# Two-Graphs and NSSDs: An Algebraic Approach

Luke Collins    Irene Sciriha

Department of Mathematics  
University of Malta

S<sup>3</sup> Annual Science Conference  
2<sup>nd</sup> March, 2018



# Structure of the Talk

## 1 Introduction

- Definition of a Graph
- Representing Graphs as Matrices
- Spectrum and Seidel Switching
- Defining Two-Graphs

## 2 Regular Two-Graphs

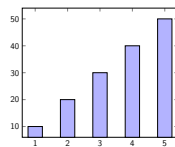
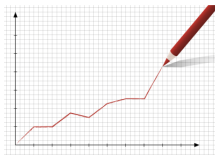
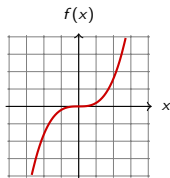
- The Involution  $\mathbf{M}$
- Descendant Form of a Regular Two-Graph
- Results about Descendants of Regular Two-Graphs

## 3 Strongly Regular Graphs

- Definition
- Structure of Descendants of Regular Two-Graphs

# Definition of a Graph

In mathematics, a *graph* is not one of these:



# Definition of a Graph

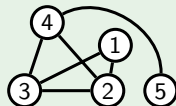
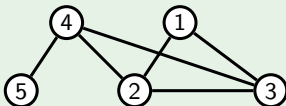
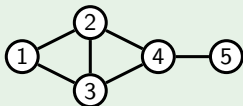
## Definition (Graph)

A **graph**  $G$  is a pair  $(V, E)$  where  $V$  is a non-empty finite set, and  $E$  is a set of unordered pairs of the elements of  $V$ .

The elements of the set  $V$  are called *vertices*, and the pairs in  $E$  are called *edges*.

## Example

$V = \{1, 2, 3, 4, 5\}$  and  $E = \{\{1, 2\}, \{1, 3\}, \{2, 3\}, \{2, 4\}, \{3, 4\}, \{4, 5\}\}$  define a graph.



# Representing Graphs as Matrices

We usually use the letter  $n$  for the number of vertices, that is,  $n = |V|$ . To encode graphs algebraically, we can use an *adjacency matrix*:

## Definition (Adjacency matrix)

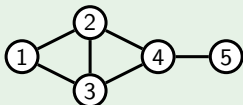
The **adjacency matrix** of a graph  $G = (V, E)$  is the  $n \times n$  matrix  $(a_{ij})$  where

$$a_{ij} = \begin{cases} 1 & \text{if vertex } i \text{ is adjacent to vertex } j, \text{ i.e. } \{v_i, v_j\} \in E \\ 0 & \text{otherwise.} \end{cases}$$

# Adjacency Matrix

## Example

The graph from the previous example has the following adjacency matrix.



$$\begin{array}{c} \begin{matrix} & 1 & 2 & 3 & 4 & 5 \\ \begin{matrix} 1 \\ 2 \\ 3 \\ 4 \\ 5 \end{matrix} & \begin{pmatrix} 0 & 1 & 1 & 0 & 0 \\ 1 & 0 & 1 & 1 & 0 \\ 1 & 1 & 0 & 1 & 0 \\ 0 & 1 & 1 & 0 & 1 \\ 0 & 0 & 0 & 1 & 0 \end{pmatrix} \end{matrix} \end{array}$$

Note that in general,

- The adjacency matrix is symmetric
- Each 1 represents an edge, and each 0 represents a non-edge
- Each entry on the diagonal is 0, since we consider simple graphs

# Seidel Matrix

Another way of encoding graphs is the *Seidel matrix*:

## Definition (Seidel matrix)

The **Seidel matrix** of a graph  $G = (V, E)$  is the  $n \times n$  matrix  $(s_{ij})$  where

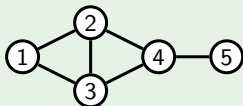
$$s_{ij} = \begin{cases} 0 & \text{if } i = j \\ -1 & \text{if vertex } i \text{ and vertex } j \text{ are adjacent} \\ 1 & \text{otherwise.} \end{cases}$$

Eventually we will work with a variant of the Seidel matrix, which we will introduce later.

## Seidel Matrix

## Example

The graph from the previous example has the following Seidel matrix.



$$\begin{array}{c}
 \begin{array}{ccccc}
 & 1 & 2 & 3 & 4 & 5 \\
 1 & \left( \begin{array}{ccccc}
 0 & -1 & -1 & 1 & 1 \\
 -1 & 0 & -1 & -1 & 1 \\
 -1 & -1 & 0 & -1 & 1 \\
 1 & -1 & -1 & 0 & -1 \\
 1 & 1 & 1 & -1 & 0
 \end{array} \right)
 \end{array}
 \end{array}$$

Note that in general, if  $\mathbf{A}$  and  $\mathbf{S}$  are the adjacency and Seidel matrices of a graph  $G$  respectively, then

$$\mathbf{S} = \mathbf{J} - \mathbf{I} - 2\mathbf{A}$$

where  $\mathbf{J}$  is the matrix consisting entirely of 1's and  $\mathbf{I}$  is the identity matrix.



# Spectrum of a Graph

The distinct eigenvalues  $\mu_1, \mu_2, \dots, \mu_s$  of a given matrix  $\mathbf{X}$  together with their multiplicities  $m_1, m_2, \dots, m_s$  form the **spectrum** of  $\mathbf{X}$ , denoted  $\mu_1^{(m_1)} \mu_2^{(m_2)} \dots \mu_s^{(m_s)}$ .

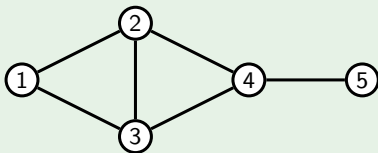
## Definition (Spectra)

- 1 The **spectrum** of a graph  $G$  is the spectrum of its adjacency matrix
- 2 The **Seidel spectrum** of a graph  $G$  is the spectrum of its Seidel matrix

# Seidel Switching

Given a graph  $G = (V, E)$  and a subset of the vertices  $U \subseteq V$ , the operation of *Seidel switching* with respect to  $U$  **exchanges all edges and non-edges** between  $U$  and  $V \setminus U$  to obtain the graph  $SS(U)$ .

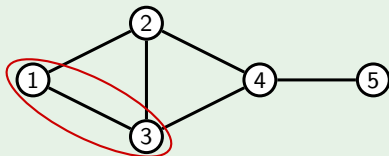
## Example



# Seidel Switching

Given a graph  $G = (V, E)$  and a subset of the vertices  $U \subseteq V$ , the operation of *Seidel switching* with respect to  $U$  **exchanges all edges and non-edges** between  $U$  and  $V \setminus U$  to obtain the graph  $SS(U)$ .

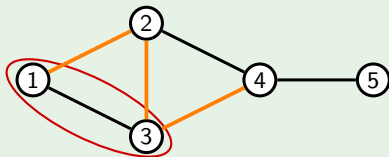
## Example



# Seidel Switching

Given a graph  $G = (V, E)$  and a subset of the vertices  $U \subseteq V$ , the operation of *Seidel switching* with respect to  $U$  **exchanges all edges and non-edges** between  $U$  and  $V \setminus U$  to obtain the graph  $SS(U)$ .

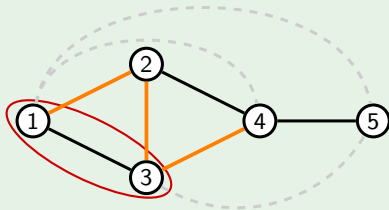
## Example



# Seidel Switching

Given a graph  $G = (V, E)$  and a subset of the vertices  $U \subseteq V$ , the operation of *Seidel switching* with respect to  $U$  **exchanges all edges and non-edges** between  $U$  and  $V \setminus U$  to obtain the graph  $SS(U)$ .

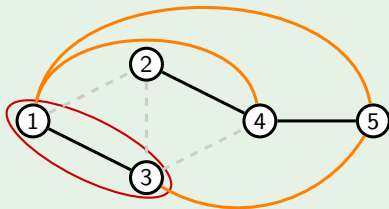
## Example



# Seidel Switching

Given a graph  $G = (V, E)$  and a subset of the vertices  $U \subseteq V$ , the operation of *Seidel switching* with respect to  $U$  **exchanges all edges and non-edges** between  $U$  and  $V \setminus U$  to obtain the graph  $SS(U)$ .

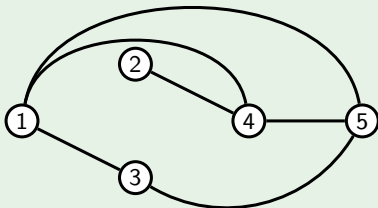
## Example



# Seidel Switching

Given a graph  $G = (V, E)$  and a subset of the vertices  $U \subseteq V$ , the operation of *Seidel switching* with respect to  $U$  **exchanges all edges and non-edges** between  $U$  and  $V \setminus U$  to obtain the graph  $SS(U)$ .

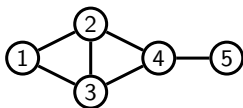
## Example



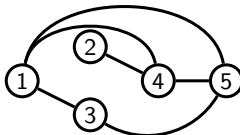
# What Seidel Switching does to the Seidel Matrix

We can assume that the vertices of the set  $U \subseteq V$  are labelled first (otherwise simply relabel the vertices). In our example, we had the following:

$G$



$SS(U)$ , where  $U = \{1, 3\}$



$$\begin{array}{c}
 1 \quad 3 \quad 2 \quad 4 \quad 5 \\
 \begin{array}{c}
 1 \\
 3 \\
 2 \\
 4 \\
 5
 \end{array}
 \left( \begin{array}{cc|ccc}
 0 & -1 & -1 & 1 & 1 \\
 -1 & 0 & -1 & -1 & 1 \\
 \hline
 -1 & -1 & 0 & -1 & 1 \\
 1 & -1 & -1 & 0 & -1 \\
 1 & 1 & 1 & -1 & 0
 \end{array} \right)
 \end{array}$$

$$\begin{array}{c}
 1 \quad 3 \quad 2 \quad 4 \quad 5 \\
 \begin{array}{c}
 1 \\
 3 \\
 2 \\
 4 \\
 5
 \end{array}
 \left( \begin{array}{cc|ccc}
 0 & -1 & 1 & -1 & -1 \\
 -1 & 0 & 1 & 1 & -1 \\
 \hline
 1 & 1 & 0 & -1 & 1 \\
 -1 & 1 & -1 & 0 & -1 \\
 -1 & -1 & 1 & -1 & 0
 \end{array} \right)
 \end{array}$$



# What Seidel Switching does to the Seidel Matrix

In general, if  $\mathbf{S}$  and  $\mathbf{S}_{SS(U)}$  are the Seidel matrices of  $G$  and  $SS(U)$ , then

$$\mathbf{S} = \left( \begin{array}{c|c} \mathbf{S}_U & \mathbf{R} \\ \hline \mathbf{R}^\top & \mathbf{S}_{V \setminus U} \end{array} \right) \iff \mathbf{S}_{SS(U)} = \left( \begin{array}{c|c} \mathbf{S}_U & -\mathbf{R} \\ \hline -\mathbf{R}^\top & \mathbf{S}_{V \setminus U} \end{array} \right).$$

In other words,  $\mathbf{S}_{SS(U)} = \mathbf{D}^{-1}\mathbf{S}\mathbf{D}$ , where  $\mathbf{D}^{-1} = \mathbf{D}$  is the diagonal matrix with  $d_{ii} = +1$  if  $i \in U$  and  $d_{ii} = -1$  otherwise.

It follows that  $\mathbf{S}$  and  $\mathbf{S}_{SS(U)}$  are similar, and therefore  $G$  and  $SS(U)$  have the same Seidel spectrum.

# Two-Graphs

The operation of Seidel switching defines an equivalence relation on the set of all graphs on  $n$  vertices.

## Definition (Two-graph)

A **two-graph** or **switching class** is an equivalence class of the Seidel switching equivalence relation.

- A two-graph on  $n$  vertices consists of all the  $n$ -vertex graphs with the same Seidel spectrum.
- The term 'two-graph' originally arose in a combinatorial context, and actually refers to a couple  $(V, \Delta)$  where  $\Delta \subseteq \binom{V}{3}$  is a collection of triples  $\{v_1, v_2, v_3\}$  with the property that any 4-subset of  $V$  contains an even number of triples of  $\Delta$ . This is known to be equivalent to our definition.

# Regular Two-Graphs

## Definition (Regular two-graph)

A two-graph is said to be **regular** if the Seidel matrix of any representative has precisely two distinct eigenvalues.

- This is a valid definition because the Seidel spectrum of any member of a two-graph is the same.
- Reverting to the combinatorial definition of 'two-graph',  $(V, \Delta)$  is said to be regular if every pair of vertices lies in the same number of triples of  $\Delta$ . This is known to be equivalent to our definition.

# The Involution $\mathbf{M}$

Suppose  $\mathbf{M}$  is a symmetric matrix which is involutory, that is,  $\mathbf{M}^2 = \mathbf{I}$ . Then

- By spectral decomposition,  $\mathbf{M}$  has eigenvalues 1 and  $-1$ .
- If  $\mathbf{M}$  is written as

$$\mathbf{M} = \left( \begin{array}{c|c} \mathbf{B} & \mathbf{v} \\ \hline \mathbf{v}^\top & -\lambda \end{array} \right),$$

then  $\mathbf{B}\mathbf{v} = \lambda\mathbf{v}$  and  $|\lambda| < 1$ .

Furthermore, if the spectrum of  $\mathbf{M}$  is  $1^{(n-k)}(-1)^{(k)}$ , then it follows by Cauchy's interlacing inequalities that the spectrum of  $\mathbf{B}$  is

$$1^{(n-k-1)}(-1)^{(k-1)}\lambda^{(1)}.$$

$$\mathbf{M} = \alpha \mathbf{S} - \lambda \mathbf{I}$$

If  $\mathbf{S}$  is the Seidel matrix of a regular two-graph on  $n$  vertices with eigenvalues  $\mu_1, \mu_2$ , then

$$\mathbf{M} = \alpha \mathbf{S} - \lambda \mathbf{I}$$

where

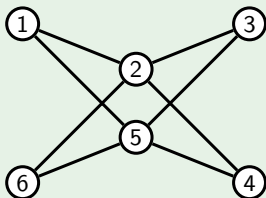
$$\alpha = \frac{2}{\mu_1 - \mu_2} \quad \text{and} \quad \lambda = \frac{\mu_1 + \mu_2}{\mu_1 - \mu_2}$$

is an involution.

- This matrix still gives us an encoding of the graph.
- $\mu_1 \mu_2 = 1 - n$ .

$$\mathbf{M} = \alpha \mathbf{S} - \lambda \mathbf{I}$$

### Example ( $K_{2,4}$ )



Seidel spectrum:  $(-1)^5(5)^1$

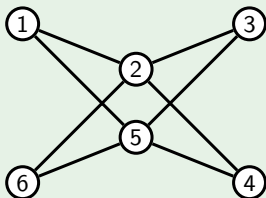
$$\alpha = \frac{2}{\mu_1 - \mu_2} = -\frac{1}{3}$$

$$\lambda = \frac{\mu_1 + \mu_2}{\mu_1 - \mu_2} = -\frac{2}{3}$$

$$\mathbf{S} = \begin{pmatrix} 0 & -1 & 1 & 1 & -1 & 1 \\ -1 & 0 & -1 & -1 & 1 & -1 \\ 1 & -1 & 0 & 1 & -1 & 1 \\ 1 & -1 & 1 & 0 & -1 & 1 \\ -1 & 1 & -1 & -1 & 0 & -1 \\ 1 & -1 & 1 & 1 & -1 & 0 \end{pmatrix}$$

$$\mathbf{M} = \alpha \mathbf{S} - \lambda \mathbf{I}$$

### Example ( $K_{2,4}$ )



Seidel spectrum:  $(-1)^5(5)^1$

$$\alpha = \frac{2}{\mu_1 - \mu_2} = -\frac{1}{3}$$

$$\lambda = \frac{\mu_1 + \mu_2}{\mu_1 - \mu_2} = -\frac{2}{3}$$

$$\mathbf{M} = \alpha \mathbf{S} - \lambda \mathbf{I} = \begin{pmatrix} 2/3 & 1/3 & -1/3 & -1/3 & 1/3 & -1/3 \\ 1/3 & 2/3 & 1/3 & 1/3 & -1/3 & 1/3 \\ -1/3 & 1/3 & 2/3 & -1/3 & 1/3 & -1/3 \\ -1/3 & 1/3 & -1/3 & 2/3 & 1/3 & -1/3 \\ 1/3 & -1/3 & 1/3 & 1/3 & 2/3 & 1/3 \\ -1/3 & 1/3 & -1/3 & -1/3 & 1/3 & 2/3 \end{pmatrix}$$

# Descendant Form

Every two-graph on  $n$  vertices has a class representative of the form  $D \dot{\cup} K_1$  where  $D$  is a graph on  $n - 1$  vertices.

## Definition (Descendant)

Any two-graph representative of the form  $D \dot{\cup} K_1$  is said to be in *descendant form*, and the component  $D$  is said to be a *descendant* of the two-graph.

## Obtaining a Descendant Form

Consider a representative  $(V, E)$  which is not in descendant form.

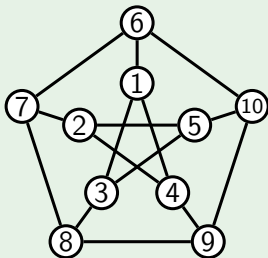
- 1 Pick any vertex  $v \in V$ .
- 2 Let  $U$  be the set of all neighbours of  $v$ .
- 3 Then the vertex  $v$  is isolated in  $SS(U)$ .



# Descendant Form

## Example (The Petersen Graph)

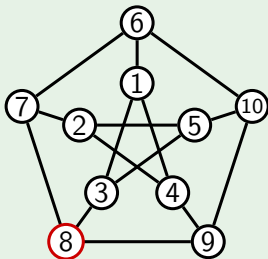
The famous Petersen graph is contained in a regular two-graph.



# Descendant Form

## Example (The Petersen Graph)

The famous Petersen graph is contained in a regular two-graph.

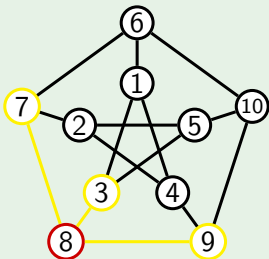


Let us isolate vertex 8.

# Descendant Form

## Example (The Petersen Graph)

The famous Petersen graph is contained in a regular two-graph.

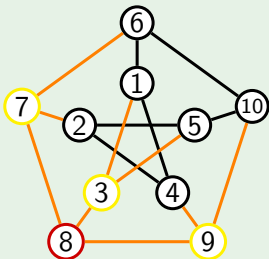


Let us isolate vertex 8. Its set of neighbours is  $U = \{7, 3, 9\}$ .

# Descendant Form

## Example (The Petersen Graph)

The famous Petersen graph is contained in a regular two-graph.

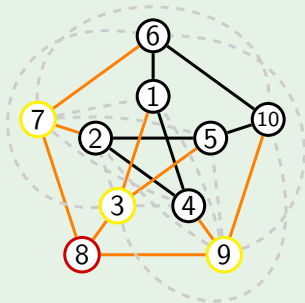


Let us isolate vertex 8. Its set of neighbours is  $U = \{7, 3, 9\}$ . Now we focus on the edges between  $U$  and  $V \setminus U$ .

# Descendant Form

## Example (The Petersen Graph)

The famous Petersen graph is contained in a regular two-graph.



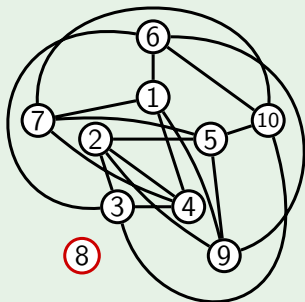
Let us isolate vertex 8. Its set of neighbours is  $U = \{7, 3, 9\}$ . Now we focus on the edges between  $U$  and  $V \setminus U$ . And the non-edges.



# Descendant Form

## Example (The Petersen Graph)

The famous Petersen graph is contained in a regular two-graph.

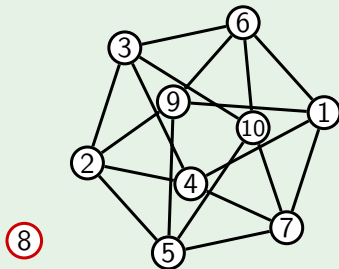


Let us isolate vertex 8. Its set of neighbours is  $U = \{7, 3, 9\}$ . Now we focus on the edges between  $U$  and  $V \setminus U$ . And the non-edges. Switch edges and non-edges. Obtain  $SS(U)$ .

# Descendant Form

## Example (The Petersen Graph)

The famous Petersen graph is contained in a regular two-graph.



Let us isolate vertex 8. Its set of neighbours is  $U = \{7, 3, 9\}$ . Now we focus on the edges between  $U$  and  $V \setminus U$ . And the non-edges. Switch edges and non-edges. Obtain  $SS(U)$ . Move vertices around to look nicer.



# Results about Descendants of Regular Two-Graphs

Using the fact that  $\mathbf{M}^2 = \mathbf{I}$ , we easily obtain the following known results for descendants of regular two-graphs.

- 1  $D$  is a  $\rho$ -regular subgraph, each vertex having degree

$$\rho = \frac{n}{2} - \frac{\lambda}{\alpha} - 1.$$

- 2 Substituting for  $\alpha$  and  $\lambda$ , we also get that  $n$  and  $\mu_1 + \mu_2$  have the same parity (even/odd).

## Results and Descendants of a Regular Two-Graphs

We prove the first result, that  $D$  is  $\rho$ -regular with  $\rho = \frac{n}{2} - \frac{\lambda}{\alpha} - 1$ .

### Proof.

Let the Seidel eigenvalues of  $G$  be  $\mu_1$  and  $\mu_2$ , where  $G$  is in descendant form. Using the values of  $\alpha$  and  $\lambda$ , the first and last rows of the involution  $\mathbf{M}$  are of the form

$$\begin{array}{l} \text{Row 1} \\ \text{Row } n \end{array} \begin{pmatrix} -\lambda & \pm\alpha & \pm\alpha & \cdots & \pm\alpha & \alpha \\ & & \vdots & & & \\ \alpha & \alpha & \alpha & \cdots & \alpha & -\lambda \end{pmatrix}$$

where we are assuming that the last row corresponds to the isolated vertex. The number of  $-\alpha$ 's in row 1 is the degree of vertex 1. Since  $\mathbf{M}^2 = \mathbf{I}$ , the inner product  $\langle \text{Row 1}, \text{Row } n \rangle = 0$ .

# Results and Descendants of a Regular Two-Graphs

We prove the first result, that  $D$  is  $\rho$ -regular with  $\rho = \frac{n}{2} - \frac{\lambda}{\alpha} - 1$ .

Proof.

$$\begin{array}{l} \text{Row 1} \\ \text{Row } n \end{array} \begin{pmatrix} -\lambda & \pm\alpha & \pm\alpha & \cdots & \pm\alpha & \alpha \\ & & \vdots & & & \\ \alpha & \alpha & \alpha & \cdots & \alpha & -\lambda \end{pmatrix}$$

$$\langle \text{Row 1}, \text{Row } n \rangle = 0 \implies -\alpha\lambda - (n-2)\alpha^2 - 2\rho_1\alpha - \alpha\lambda = 0$$

where  $\rho_1$  denotes the degree of vertex 1.

Note that  $\rho_1$  is independent of the vertex label 1, since

$$\langle \text{Row 1}, \text{Row } i \rangle = 0$$

for all  $1 \leq i \leq n-1$ . Thus  $D$  is  $\rho$ -regular. □

# Strongly Regular Graphs

**Recall:** A graph is called *regular* if all the vertices are of the same degree.

## Definition (Strongly regular graph)

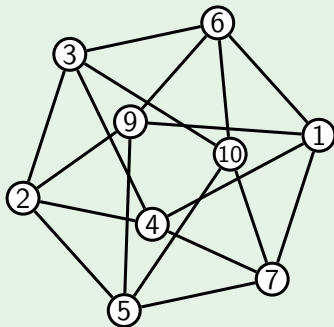
A graph  $G$  is said to be a strongly regular graph or an  $\text{srg}(n, \rho, e, f)$  if:

- 1 it has  $n$  vertices,
- 2 each vertex has degree  $\rho$ ,
- 3 every two adjacent vertices have  $e$  common neighbours, and
- 4 every two non-adjacent vertices have  $f$  common neighbours.

# Strongly Regular Graphs

## Example (Descendant of Petersen Graph)

The descendant from the last example is an  $\text{srg}(9, 4, 1, 2)$ .



## Structure of Descendants of Regular Two-Graphs

Consider a descendant form  $D \dot{\cup} K_1$  of a regular two-graph, and for any two adjacent vertices, let  $\tilde{e}$  denote the number of common neighbours and let  $\tilde{\bar{e}}$  denote the number of common non-neighbours.

Similarly, for any two non-adjacent vertices, let  $\tilde{f}$  denote the number of common neighbours and let  $\tilde{\bar{f}}$  denote the number of common non-neighbours.

By considering the rows of  $\mathbf{M}$  we obtain the following formulæ:

- $\tilde{e} + \tilde{\bar{e}} = \frac{1}{2}(n-2) - \frac{\lambda}{\alpha}$   
 $\tilde{e} - \tilde{\bar{e}} = 2\rho - n$
- $\tilde{f} + \tilde{\bar{f}} = \frac{1}{2}(n-2) + \frac{\lambda}{\alpha}$   
 $\tilde{f} - \tilde{\bar{f}} = 2\rho - (n-2)$

From these it follows that  $\tilde{e}$ ,  $\tilde{\bar{e}}$ ,  $\tilde{f}$  and  $\tilde{\bar{f}}$  are invariant for any pair of adjacent/non-adjacent vertices.

# Structure of Descendants of Regular Two-Graphs

From the formulæ obtained previously, we get the following results.

- Given a descendant form  $D \dot{\cup} K_1$  of a regular two-graph on  $n$  vertices, then  $D$  is an  $\text{srg}(n-1, \rho, e, f)$  where

$$e = \tilde{e} \quad \text{and} \quad f = \tilde{f} = \frac{\rho}{2}.$$

- $n$  must be even.
- $\frac{\lambda}{\alpha}$  is an integer.

THE END